#### SMOOTHNESS INDEX OF THEMATIC MAPS Claudio L. Bazzi, Juliano. Carnieletto, and Davi M. Rocha Universidade Tecnológica Federal do Paraná (UTFPR) Medianeira/PR. Brazil Eduardo G. Souza Universidade Estadual do Oeste do Paraná (Unioeste) Cascavel/ PR, Brazil \* *Corresponding author (godoy@unioeste.br)* ABSTRACT The thematic maps are generated with the intention of representing the variables in study, being used interpolators to determine their values in places not

sampled. The kriging is usually considered the best interpolation method, but several works found good results for the inverse distance and inverse-square-distance methods. The evaluation of the best method usually consists in comparing the estimated values for interpolation with the sampled values. However, the visual aspect of the map created is also relevant, and the smoothness of the contour curves, an item to be taken into account, because it facilitates the visual interpretation and the site-specific management of agricultural inputs in the agriculture. The objective of this work was to evaluate the smoothness of three thematic maps, created with different interpolators, built through corn yield data in an area of 13.2 ha. The selected interpolators were kriging, inverse of the distance, and inverse-square-distance. The evaluation was accomplished through the smoothness index, proposed in this article that calculates the frequency of classes change of the thematic map in the horizontal, vertical and diagonal directions through software built for this purpose. The index proved efficient in the determination of the smoothness of thematic maps. 

# 38 Keywords: management zones, interpolators, yield map

## **INTRODUCTION**

The thematic map is the main instrument in the process of making decisions 46 47 in the precision agriculture (PA). The most common type of thematic map is the yield map, and it is a georeferenced graphich display of the yield of a culture per 48 area unit. According to Molin (2001), the PA has a closed cycle of tasks which 49 must be preferentially initiated through the yield map, which integrates the effects 50 of several spatial variables such as soil properties, fertilizers rate, topographic 51 attributes, atmosphere conditions and illnesses infestation. According to Michelan 52 et al. (2007), the crop is formed by various processes in which errors can occur, 53 for which reason a filtering of data methodology becomes necessary for the 54 attainment of reliable maps. Among the main types of error, we can mention: time 55 of delay, filling and emptying time, positioning of the GPS and effective shorter 56 length of the crop than that showed in the yield monitor. Based on the yield map it 57 is possible to define regions that may have been influenced by some variable on 58 which the yield depends, enabling the application of such attribute in a 59 differentiated manner in accordance with the estimated necessity (Cordeiro et al., 60 2001). 61

The thematic maps, such as the yield map and those of related attributes are 62 elaborated taking into consideration samples collected in the evaluated area. In 63 order to estimate the values in sites not sampled, interpolators are utilized, being 64 the main ones the kriging, the inverse distance, and the inverse square distance. 65 Jones et al. (2003) mention that many articles were published comparing 66 different methods of interpolation in a large variety of types of data. These articles 67 utilized various types of data: atmosphere, contents of clay and pH of the soil; 68 rain precipitation; and elevation. Most of these studies involved two-dimensional 69 methods of interportation. The methods studied in bigger depth were kriging and 70 the inverse distance raised to a power (IDP). Eight studies showed that the kriging 71 was the best method, and that even when the kriging proved more effective "in 72 average", the IDP was more effective under determined circumstances. Two of 73 the studies concluded that the IDP was more effective than the kriging and six of 74 the studies showed a very minor difference between kriging and IDP. 75

Bazzi et al. (2008) evaluated the decrease of the precision in yield maps 76 obtained in areas where combine harvesters not equipped with yield monitors 77 associated with combine harvesters equipped with yield monitor were utilized. 78 The decrease in the number of measurements and therefore of the number of 79 points monitored decreased the precision of the maps in the inverse square 80 distance and kriging interpolation methods, being the influence on the kriging 81 more expressive. According to Balastreire et al. (1998), small errors end up 82 having little practical relevance, since what effectively matters is to have regions 83 which can be managed in a differentiated manner and the knowledge of which 84 attribute must be provided for the increase of the yield in that specific region. In 85 the elaboration of thematic maps the appearance of small regions inside other 86 much larger regions and with very different values which render the visual 87 88 interpretation and its utilization in the site-specific management of the agriculture inputs difficult is frequent. 89

In practice, the site-specific management of these sub-areas is usually unfeasible and it would be desirable that the interpolation process would eliminate

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them. However, the visual analysis is subjective and therefore an index which can characterize this situation is desirable. The purpose of this work was to evaluate the smooth index of thematic maps proposed by Souza et al.(2009) and utilize it to evaluate the smoothness in twelve thematic maps, created by the kriging interpolators (KRI), inverse distance (ID), inverse square distance (IQD), referring to 4 distinct areas.

## MATERIAL AND METHODS

102 The yield of corn and soybean cultures of four areas (24° 57' S e 53° 27' W, average elevation of 750 m) located in the rural zone of the city of Cascavel, state 103 of Paraná, Brazil, was evaluated in the period from 2003 to 2007. The harvesting 104 was carried out with the utilization of a combine harvester New Holland<sup>®</sup> TC 57, 105 equipped with yield monitor AgLeader<sup>®</sup> PF 3000. After the collection of data, the 106 elimination of sampling points presenting very high or very low yield was done, 107 following the procedure adopted by BLACKMORE & MOORE (1999). These 108 points were probably influenced by errors sources such as: delay time, filling and 109 emptying time, positioning of the GPS and effective shorter length of the crop 110 than that showed in the yield monitor. Data with very high or very low water 111 content, originated by humidity sensor reading errors were also eliminated. The 112 maps were elaborated with the utilization of filtered data for each area (Table 1). 113

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### 115 **Table 1 Metadata collection and filtering**

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Culture/Havest	Simbology	Area	Average	Time*	Gross	FinalTotal	Point	Sampling
		(ha)	Speed	(s)	Total	Points	number	Density
			$(km h^{-1})$		Points		reduction	(points ha <sup>-1</sup> )
Soybean 2002/2003	Soybean/03	14.8	5.3	1.00	19,351	18,306	5.4%	1,237
Corn 2003/2004	Corn/04	30.3	4.0	3.00	14,693	13,738	6.5%	453
Soybean 2005/2006	Soybean/06	45.3	5.5	3.00	8,089	7,960	1.6%	176
Soybean 2006/2007	Soybean/07	30.0	5.7	3.00	6,037	5,246	13.1%	175

\*Time - collection period between the two samples in seconds.

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The data were analyzed statistically through descriptive and exploratory 118 data analysis with the calculation of the average, median, minimum, maximum, 119 standard deviation and coefficient of variation. For the verification of the 120 normality of data, the tests of Anderson-Darling and Kolmogorov-Smirnovs at the 121 level of 5% of significance were utilized, being considered normal data which 122 presented normality in at least one of the tests. The coefficient of variation (CV) 123 was considered low when  $CV \le 10\%$  (homocedastici ty), medium when 124  $10\% < CV \le 20\%$ , high when  $20\% < CV \le 30\%$ , and very high when CV > 30%125 (heterocedasticity) (PIMENTEL-GOMES & GARCIA, 2002). 126

In the construction of semivariograms the software ArcView 9.2 was utilized in the ordinary kriging module. The theoretical models spherical, exponential and Gaussian were adjusted to the semivariograms through the method OLS (*Ordinary Last Square*), standard of the software utilized, which

also provides the cross-validation as a tool of selection of the most adequate 131 model of theoretical semivariogram. Among the estimates provided by the 132 software for the evaluation of models, we have the reduced mean-square error 133  $(\overline{ER}, \text{ equation 1})$  reduced error standard deviation (S<sub>ER</sub>, equation 2). In order to 134 avoid the situation in which the estimates point to different models, a new 135 estimate called Index of Comparison of Errors (ICE, equation 3) was proposed, 136 which in the selection of *j* models provides a lower value the lowest closest to 137 zero is the  $\overline{ER}$  (Reduced Mean-Square Error) and the closest to one is the S<sub>ER</sub> 138 (Reduced Error Standard Deviation). Therefore in the selection of various models, 139 the one presenting the lowest ICE is considered the best model. 140 141

$$\overline{ER} = \frac{1}{n} \sum_{i=1}^{n} \frac{Z(s_i) - \hat{Z}(s_{(i)})}{\sigma(\hat{Z}(s_{(i)}))}$$
[1]

$$S_{ER} = \sqrt{\frac{1}{n} \sum_{i=1}^{n} \frac{|Z(s_i) - \hat{Z}(s_{(i)})|}{\sigma(\hat{Z}(s_{(i)}))}}$$
[2]

Where  $\sigma(\hat{Z}(s_{(i)}))$  is the kriging deviation error in the point  $s_i$ , without considering the observation  $Z(s_{(i)})$ .

$$ICE_i = A + B$$
[3]

$$A = \begin{cases} \frac{ABS(SME)i}{MAX(ABS(SME))}, when \ MAX(ABS(\overline{ER})) > 0 \end{cases}$$
[4]

$$A = \begin{cases} \frac{ABS(SDRME)i}{MAX(ABS(SDRME))}, & when MAX(ABS(S_{ER})) > 0\\ 1, & when the contrary occurs \end{cases}$$
[5]

 $ICE_i$  is the index of comparison of errors for the model *i*.

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The degree of spatial dependence was classified in accordance with the Spatial Dependence Index (IDE, Equation 6), and CAMBARDELLA *et al.* (1994) proposed the following intervals to evaluate the percentage of the semivariance of the nugget effect:  $\leq 25$  % - strong spatial dependence; between 25 % and 75 % moderate spatial dependence and  $\geq 75$  % - weak spatial dependence.

$$IDE = \frac{C_0}{C_1 + C_0} 100$$
 [6]

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In the elaboration of thematic maps, the interpolators inverse distance, inverse square distance and kriging were utillized, using the software Surfer 9 (Bazzi et al., 2008). After interpolated, the maps were classified with the utilization of 5 classes (as suggested by Molin, 2001). After the superficial evaluation of each map created, each of them was exported to a *database file* (dbf).

The smoothness index (SI, equation 7), proposed by Souza (2009), calculates the frequency of the change of classes in the thematic maps in the horizontal, vertical and diagonal directions, pixel per pixel, through a software
created for this purpose. In the hypothesis that the map had a totally homogeneous
area, a smooth index of 100% would be obtained due to the absence of change of
class. In the same way, if the map was generated with random values, the smooth
index would present a value close to zero.

$$SI = 100 - \left( \left( \frac{\sum_{i=1}^{l} NM_{Hi}}{4P_{H}} + \frac{\sum_{i=1}^{c} NM_{Vi}}{4P_{V}} + \frac{\sum_{i=1}^{n} NM_{Ddi}}{4P_{Dd}} + \frac{\sum_{i=1}^{n} NM_{Dei}}{4P_{De}} \right) * 100 \right)$$
[7]

163 where,  $NM_{HI}$ - Number of changes in the horizontal line i;  $NM_{VI}$ - Number of 164 changes in the vertical line j;  $NM_{DdI}$ - Number of changes in the right diagonal in 165 the diagonal k;  $NM_{DeI}$ - Number of changes in the left diagonal in the diagonal l; 166  $P_{HI}$ - Number of pixels in the horizontal;  $P_{V}$ - Possibility of change in the vertical; 167  $P_{Dd}$ - Possibility of change in the right diagonal;  $P_{De}$ - Possibility of change in the 168 left diagonal.

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For evaluation and execution of the process referring to the calculation of the index, the Smoothness Index Calculator 2.0 (SIC2.0, Figure 1), utilizing Java language and the technique of support to the development IDE Eclipse, was utilized.

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Figure 1. Visual environment Smoothness Index Calculator 2.0 (SIC2.0).

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The program enables the set up of configurations (Figure 2) so that it is possible to alter the analysis file, to select the quantity of classes or blocks, to alter the change of the colors of the classes and to indicate the maximum and minimum values.

🛎 SIC 2.0		
Preview	Smothness Index Configuration	
<b>Range</b> 1800	Number of	fblocks
File	]	
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Figure 2. Configuration display of the software Smoothness Index
 Calculator 2.0 (SIC2.0).

## **RESULTS AND DISCUSSION**

The descriptive analysis of data (Table 5) showed that the four data sets (one for each stand) did not have normal distribution. The productive values presented average (soybean/06, CV = 16.2%; soybean/07, CV = 13.1%) and high (corn/04, CV = 28.3% and soybean/03 CV = 24.3%) variabilities. The maximum value varied from 220% (soybean/07) to 556% (corn/04) from the minimum value, which backs up the premise that even in small areas (from 15 to 45 ha) the variability of the data is very large.

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197 Table 5. Descriptive statistics for the yield data

Culture	Minimum (kg ha <sup>-1</sup> )	Mean (kg ha <sup>-1</sup> )	Median (kg ha <sup>-1</sup> )	Maximum (kg ha <sup>-1</sup> )	StDev (kg ha <sup>-1</sup> )	CV (%)	Amplitude (kg ha <sup>-1</sup> )	Skewness	Kurtosis	N*
Soybean/03	675	1,903	1,836	3,564	540	28.3	2,889	0.56 c	0.01 A	No
Corn/04	1,646	5,549	5,667	9,147	1,350	24.3	7,501	-0.60 c	-0.12 A	No
Soybean/06	2,061	3,741	3,788	5,422	610	16.2	3,361	-0.26 c	-0.09 A	No
Soybean/07	2,414	3,852	3,872	5,314	500	13.1	2,900	1.27 c	11.2 A	No

198 Skewness: symmetric (a), positive skewness (b), negative skewness (c);

199 Kurtosis: mesokurtic (A), platykurtic (B), leptokurtic (C);

200 StDev – Standard deviation; CV – Coefficient of Variation;

<sup>201</sup> \* Normality tested with Anderson-Darling and Kolmogorov-Smirnovs tests.

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The maps of yield score referring to Soybean/2006 and Soybean/2007 (Figure 3) presented gaps in the data survey, contrary to the Soybean/2003 and Corn/2004. However, this fact could be compensated by the interpolation of data.

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Figure 3 Score Maps 209

In the geostatistical analysis (Table 3), the method of cross-validation 210 pointed to the exponential model as the best model for adjustment of the 211 semivariograms (Figure 4), as it provided the lowest ICE in all the cases. Date 212 presented mostly medium spatial dependence because for most of cases the spatial 213 214 dependence index (SDI) varied in the interval from 25 to 75% (CAMBARDELLA et al., 1994). 215

Variable	Model	Co	C1	Sill	a (m)	SDI	$\overline{ER}$	$\mathbf{S}_{\mathrm{ER}}$	ICE
	Gaussian	0.2292	0.0731	0.3023	120.4	75.8%	-0.00427	0.8712	2.00
Soybean/03	Exponential	0.1912	0.1128	0.3040	142.6	62.9%	-0.003	0.9098	1.40
	Spherical	0.2148	0.0871	0.3019	138.3	71.1%	-0.00374	0.8839	1.77
Corn/04	Gaussian	1.2588	1.3694	2.6282	653.9	47.9%	0.00079	0.82	1.75
	Exponential	0.9033	1.4391	2.3424	748.2	38.6%	0.00099	0.9405	1.27
	Spherical	1.0609	1.4770	2.5379	748.2	41.9%	0.00105	0.8814	1.66
Soybean/06	Gaussian	0.3010	0.0942	0.3952	410.1	76.2%	-0.00617	0.9069	2.00
	Exponential	0.2728	0.1400	0.4128	727.6	66.1%	-0.00472	0.9359	1.45
	Spherical	0.2826	0.1109	0.3935	461.8	71.8%	-0.00524	0.9257	1.65
Soybean/07	Gaussian	0.2419	0.0248	0.2667	846.5	90.7%	0.00322	0.9034	1.91
	Exponential	0.2327	0.0297	0.2624	846.5	88.9%	0.00337	0.9168	1.86
	Spherical	0.2375	0.0261	0.2636	846.5	90.0%	0.0033	0.9099	1.95

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\* C0 – Nugget Effect; C1 – Contribution; Sill – C0 +C1; a – Range; SDI – Spatial 217

Dependence Index;  $\overline{ER}$  – Average Error; S<sub>ER</sub> – Average Error Standard Deviation. 218



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For each data set (soybean/2003, Figure 5; corn/2004,Figure 6; soybean/2006, Figure 7; soybean/2007, Figure 8), three thematic maps referring to the yield were generated, utilizing the interpolation methods inverse distance (ID), inverse square distance (ISD) and kriging (KRI)



Figure 5 Yield map for the crop Soybean/03, utilizing the interpolation methods inverse distance (ID), inverse square distance (ISD) and kriging (KRI).





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Figure 7 Yield map for the crop Soybean/06, utilizing the interpolation methods inverse distance (ID), inverse square distance (ISD) and kriging (KRI).



Figure 8 Yield map for the crop Soybean/07, utilizing the interpolation methods inverse distance (ID), inverse square distance (ISD) and kriging (KRI).

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For the cultures soybean/03 and soybean/06 and corn/04 (Table 4), the 237 kriging interpolator provided the maps with the highest smoothness (higher SI), 238 and the ISD interpolator presented the lowest smoothness indexes. For the year 239 2007, in the culture of soybean, the ISD interpolator presented a higher 240 smoothness index, probably influenced by the shorter amplitude and data standard 241 deviation in relation to the other cultures. It is further noticeable that this set of 242 data presented asymmetry and kurtosis indexes more significant than the other 243 sets. 244

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Table 4 Smooth Index in relation to the interpolator (inverse distance (ID),
 inverse square distance (ISD) and kriging (KRI)) for each set of data

2-77	mverse square dista	lice (IDD) and KI		n eden set of dat	i			
	Product/Crop	Soybean/03	Corn/04	Soybean/06	Soybean/07			
	ID	73%	86%	88%	<mark>88%</mark>			
	IQD	<mark>61%</mark>	71%	76%	<mark>94%</mark>			
	KRI	<mark>79%</mark>	<mark>88%</mark>	<mark>90%</mark>	89%			
248	Minimum valu	e 🗖 Iaximum	value					
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251		CON	CLUSIONS					
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253	Through the smoothness index, it can be concluded that in three of the four							
254	cases analysed the kriging interpolator presented the maps with the highest							
255	smoothness and the inverse square distance interpolator, the maps with the lowest.							
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262	office of State of S	cience, Technolo	gy and Highe	r Education - SE	ETI/PR, Capes			
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